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[71]Name of Applicant:

1)St. Martin's Engineering College

Address of Applicant: St.Martin's Engineering College, Dhulapally Kompally Secunderabad Name of Applicant : NA Address of Applicant : NA (72)Name of Inventor:

1)Dr. P. Santosh Kumar Patra Professor, Dept. of CSE, SMEC
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad2)Mr. K. V. Govardhan Rao, EEE 2)Mr. K. V. Govardhan Rao, EEE
Address of Applicant :St. Maris Engineering College, Dhulapally Kompally Secunderabad --3)Mr. B. Sreeram Student EEE
Address of Applicant :St. Martin's Engineering College, Dhulapally Kompally Secunderabad --4)Mr. A. Tejith Reddy Student EEE
Address of Applicant :St. Martin's Engineering College, Dhulapally Kompally Secunderabad --5)Ms. G. Nandini Student EEE :H02J0007000000, B25J0005000000, G05D0001020000, B63G0008000000. (51) International classification 5)Ms. G. Nandim Student E.E.
Address of Applicant :S. Martin's Engineering College, Dhulapally Kompally Secunderabad --6)Ms. A. Simaran Student E.E.
Address of Applicant :S. Martin's Engineering College, Dhulapally Kompally Secunderabad --7)Ms. K. Tejaswini Student E.E.
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad ---F41H0007000000 :PCT/// :01/01/1900 : NA (86) International Application No (80) International Application No Filing Date (87) International Publication No (61) Patent of Addition to Application Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad ----SyMr. CH. Kumar Teja Student EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad ----9)Ms. K. Lasya Student EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad ----10)Mr. K. Abhinav Student EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad ----11)Mr. P. Vinos Student EEE :NA Filing Date :NA (62) Divisional to Application Number Filing Date 11)Mr. P. Vinod Student EEE 11)Mr. P. Vinod Student EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad
12)Mrs. T. V. Sai Kalyani EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad
13)Ms. P. Sri Varsha Student EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad
14)Mr. V. Karthik Reddy Student EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad
15)Ms. D. Sri Divya Student EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad
16)Mr. K. Mallikarjuna Reddy, Student, EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad
16)Mr. K. Mallikarjuna Reddy, Student, EEE
Address of Applicant :St.Martin's Engineering College, Dhulapally Kompally Secunderabad

(57) Abstract:

This project focuses on the planning associated construction of an improvement charging system for Li–Po batteries by suggests that of half-track star panels. Thus, the implementation of an entire energy management system applied to a robotic exploration vehicle is advance. The projected system was tested on the robotic platform an autonomous remote-controlled exploration vehicle specialized in recognition. The interest of this robotic system lies within the style thought, supported a wise microcontroller. On this basis, our proposal makes a twofold vital contribution. The aim is finishing the method of charging electric battery severally whereas the opposite battery provides all the energy consumed by the robotic vehicle. The projects mainly works on when the battery supply in between 8-12v then only robot moves through Bluetooth, when the battery in between 8-4v then only load on, in case supply goes to below 4v then battery charged from solar.

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